

Semi-blind Decoding of Multi-finger Movements Using M1 Neurons

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Abstract—We present an evidence of correlation between single and multi-finger movements and also attempt a challenging task of semi-blind decoding of neural data with minimum training of the neural decoder. Data were collected from 115 task-related neurons in M1 of a trained rhesus monkey performing flexion and extension of each finger and the wrist (12 single and 6 two-finger-movements). By exploiting correlation of temporal firing pattern between movements, we found that correlation coefficient for physically related movements pairs is greater than others; neurons tuned to single finger movements increased their firing rate when multi-finger commands were instructed. According to this knowledge, neural semi-blind decoding is done by choosing the greatest and the second greatest likelihood for canonical candidates. We achieved a decoding accuracy about 90% for multiple finger movement without corresponding training data set. These results suggest that only with the neural activities on single finger movements can be exploited to control dexterous multi-fingered neuroprosthetics.

I. INTRODUCTION

We exploit correlations in monkey M1 neurons between finger flexing/extending movements. If there is a neural correlation between single and multi-finger movements, the correlation makes it possible to decode multi-finger movements only with single finger related neural information.

II. METHODS & EXPERIMENTAL RESULTS

We measured relation between the peri-event time histograms corresponding two movements of a given neuron by the Pearson's correlation coefficient. For physically related single and multi-finger pairs, the correlation coefficient values were as high as 0.7 and, for uncorrelated pairs the correlation coefficient values were as low as 0.3 or less. Thus,

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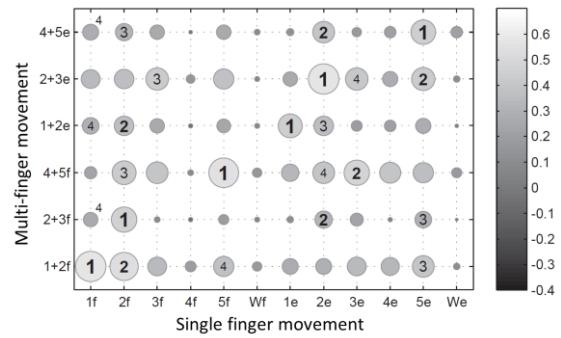


Figure 1. Neural correlation of 20 high responding neurons between single and multi-finger movement during ‘Onset’ period. The size and the intensity are proportional to correlation coefficient between PETHs.

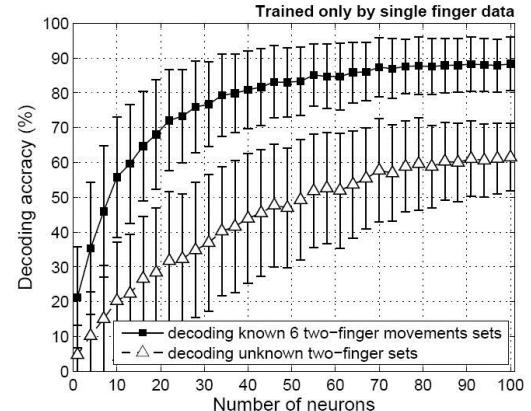


Figure 2. Blind multi-finger decoding accuracy. The upper curve is the decoding accuracy without multi-finger training data but assuming six multi-finger types are known. The lower curve is the accuracy without multi-finger training data set and no assumption on multi-finger types.

fundamental neural network for both single and multiple finger movement exist. Furthermore, we proposed a blind neural decoder for multi-finger movements which needs training with just single finger movement data. Assuming that 6 two-finger movement sets are known, the decoding accuracy was found to be as high as 90% with 100 neurons.

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